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834 Lecture 7

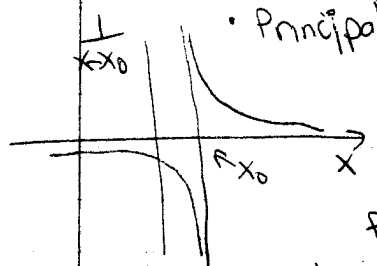
Lecture plan: (many small, related topics)

- Comments on the midterm (63)
- Recap Legendre function \rightarrow polynomials (60), (61)
- Mathematica and differential equations (64), (65)
- Analytic continuation and gamma function (48), (66), (67)
- Harmonic functions
- Asymptotic methods
- Setting up PS#4 problems
- Solving SEqn for bound states (Numerov method)
- Fourier series introduction.

Before class:

• Start up Mathematica and bring up PS#3 notebook

• Principal value recap



$$P \int_{-\infty}^{\infty} \frac{1}{x-x_0} dx = \int_{-\infty}^{x_0-\epsilon} + \int_{x_0+\epsilon}^{\infty} \frac{1}{x-x_0} dx = 0$$
 because the areas cancel as long as we integrate symmetrically about $x=x_0$. If we have $\frac{f(x)}{x-x_0}$, the areas still cancel, because $f(x_0 \pm \epsilon) \approx f(x_0)$ and we can pull $f(x)$ outside the integral.

On board: Legendre function recap

$$(1-x^2)y'' - 2xy' + \alpha(\alpha+1)y = 0$$

consider each \uparrow general

$$y = \sum_{n=0}^{\infty} a_n x^{n+k} \Rightarrow n=0, x^{k-1} : k(k-1)a_0 = 0 \Rightarrow k=0 \text{ or } k=1$$

$$n=1, x^{k+1} : (k+1) \cdot k a_1 = 0 \Rightarrow \text{possible constraints}$$

$$k=0 \quad a_{j+2} = \frac{j(j+1) - \alpha(\alpha+1)}{(j+2)(j+1)} a_j \quad \Bigg| \quad k=1: \quad a_{j+2} = \frac{j(j+2) - \alpha(\alpha+1)}{(j+2)(j+1)} a_j$$

on a_2 ; not additional k's.

$\alpha = l$ integer (angular momentum) \Rightarrow Legendre polynomials

Here: unnormalized polynomials $y_0(x)=1, y_1(x)=x, y_2(x)=1-3x^2, \dots$

Later: $P_0(x)=1, P_1(x)=x, P_2(x)=\frac{1}{2}(3x^2-1), \dots \Rightarrow \int_{-1}^1 P_0(x)P_1(x)dx = \frac{2}{2+1} \delta_{01}$ on $[-1, 1]$

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Comments on the upcoming midterm

• Wednesday during class. Design is for one-hour exam, but you have the full 1 hour 48 minute period to do it.

• Two parts: basic problems, synthetic problems

• Basics: testing for core competencies

• what everyone needs to know to pass

• eg., δ_{ij} and ϵ_{ijk} manipulations; applying formulas on Jackson covers; knowing different types of singularities; complex manipulations (like taking n^{th} roots); applying Frobenius

what does 'analytic' entail?

"Spot the error!"

Aside: what functions have branch points? $f(z) = (z-z_0)^\alpha, \ln(z-z_0)$

• Non-analytic at $z_0 \Rightarrow$ Taylor series doesn't exist. Seen here by derivatives (eventually) blowing up at z_0 eg.

$$f(z) = (z-z_0)^{3/2}, f'(z) = 3/2(z-z_0)^{1/2}, f''(z) = \frac{3}{2} \cdot \frac{1}{2}(z-z_0)^{-1/2} \Rightarrow f''(z_0) = \infty$$

• Synthetic: putting ideas/techniques together; applying to new situations

• Based on topics seen in homework problems

• Names, setting up problems, applying tools like $\delta_{ij}, \epsilon_{ijk}$, definitions and notation

• You will be given Jackson covers; any needed integrals like $\int_0^\infty e^{-az} dz$

• You will not be given (must know these!)

$$e^{iz} = \cos z + i \sin z = 1 + iz + \frac{z^2}{2!} + \dots \quad (1+z)^\alpha = 1 + \alpha z + \dots \quad |z| < 1$$

$$\epsilon_{abc} \epsilon_{ade} = \delta_{bd} \delta_{ce} - \delta_{be} \delta_{cd}$$

"All numbers in ϵ_{abc} must be different. If first indices are the same, then either the next two and the last two are the same, or the 2nd and 3rd of each are the same, with a minus sign."

• CR relations, shouldnt have to

• How to prepare: memorize.

• Go over P# 1-4 and make sure you can set up every problem without looking at solutions

• Check solutions and lecture notes for emphasis points. Remember the picky points taken off on homework and emphasized in class

Differential Equations in Mathematica: PS#3 examples

PS#3 Problem 4

note need $y''[x]$, not just y''

Try to find a general solution to PS #3, Problem 4

```

In[1]:= DSolve[x y''[x] + (1 - x) y'[x] +  $\alpha$  y[x] == 0, y, x]
Out[1]:= {{y -> Function[{x}, C[1] HypergeometricU[- $\alpha$ , 1, x] + C[2] LaguerreL[ $\alpha$ , x]]}}

```

Perhaps not so helpful because these are general functions (look them up in the Documentation Center). To see the polynomial solutions we can try a specific value, such as $\alpha=2$:

```

In[2]:= DSolve[x y''[x] + (1 - x) y'[x] + 2 y[x] == 0, y, x]
Out[2]:= {{y -> Function[{x}, (2 + (-4 + x) x) C[1] +  $\frac{1}{4}$  C[2] (3 ex - ex x + 2 ExpIntegralEi[x] - 4 x ExpIntegralEi[x] + x2 ExpIntegralEi[x])]}]}

```

Ok, that gives our polynomial and another cryptic function: ExpIntegralEi (look it up!).

Define a function that let's us easily change the integer:

```

In[3]:= prob4[n_] := DSolve[x y''[x] + (1 - x) y'[x] + n y[x] == 0, y, x]

```

Test it

```

In[4]:= prob4[0]
Out[4]:= {{y -> Function[{x}, C[2] + C[1] ExpIntegralEi[x]]}}

```

Good, but awkward. Let's strip out the excess baggage:

```

In[5]:= prob4full[n_] := (y[x] /. DSolve[x y''[x] + (1 - x) y'[x] + n y[x] == 0, y, x])[[1]]

```

The [[1]] gets rid of the final {}'s. It refers to a part of the equation. Look up Part in the help for examples of this very useful capability.

```

In[6]:= prob4full[0]
Out[6]:= C[2] + C[1] ExpIntegralEi[x]
In[7]:= ? ExpIntegralEi

```

ExpIntegralEi[z] gives the exponential integral function Ei(z). >>

Expand to see the logarithm

```

In[8]:= Simplify[Series[ExpIntegralEi[x], {x, 0, 4}], Assumptions -> {x > 0}]

```

```

Out[8]:= (EulerGamma + Log[x]) + x +  $\frac{x^2}{4}$  +  $\frac{x^3}{18}$  +  $\frac{x^4}{96}$  + O[x]5

```

```

In[9]:= EulerGamma // N
Out[9]:= 0.577216

```

The solution with $\ln x$ is discussed in the Arfken and Lea texts.

```

In[10] = prob4full[1]
Out[10] = (-1 + x) C[1] + C[2] (-e^x - ExpIntegralEi[x] + x ExpIntegralEi[x])

In[11] = prob4full[2]
Out[11] = (2 + (-4 + x) x) C[1] +
          1
          4 C[2] (3 e^x - e^x x + 2 ExpIntegralEi[x] - 4 x ExpIntegralEi[x] + x^2 ExpIntegralEi[x])

In[12] = prob4full[3]
Out[12] = (-6 + (-6 + x) (-3 + x) x) C[1] +
          1
          36 C[2] (-11 e^x + 8 e^x x - e^x x^2 - 6 ExpIntegralEi[x] + 18 x ExpIntegralEi[x] -
          9 x^2 ExpIntegralEi[x] + x^3 ExpIntegralEi[x])

In[13] = prob4full[4]
Out[13] = (24 + (-4 + x) x (24 + (-12 + x) x)) C[1] +
          1
          576 C[2] (50 e^x - 58 e^x x + 15 e^x x^2 - e^x x^3 + 24 ExpIntegralEi[x] - 96 x ExpIntegralEi[x] +
          72 x^2 ExpIntegralEi[x] - 16 x^3 ExpIntegralEi[x] + x^4 ExpIntegralEi[x])

```

What about non-integers?

```

In[14] = prob4full[1 / 2]
Out[14] = C[1] HypergeometricU[-1/2, 1, x] + C[2] LaguerreL[1/2, x]

```

■ PS#3 Problem 5

Ok, let's try problem 5

```

In[15] = ans5 = DSolve[4 x^2 y''[x] + 4 x y'[x] + (4 x^2 - 1) y[x] == 0, y, x]

```

```

Out[15] = {{y -> Function[{x},
  e^{-i x} C[1]
  -----
  sqrt[x]
  -
  i e^{i x} C[2]
  -----
  2 sqrt[x]
  ]}}

```

Pull out the function and convert to sines and cosines:

```

In[16] = ExpToTrig[y[x] /. ans5[[1]]] // Simplify
Out[16] =
  (2 C[1] - i C[2]) Cos[x] + (-2 i C[1] + C[2]) Sin[x]
  -----
  2 sqrt[x]

```

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(66)

Gamma function $\Gamma(z)$ — [see Chap. 8 in Arfken; Sect 2.9 in Lea]

In the solution to Laguerre's equation in problem 4 of PS#3, you found the series solution:

$$y(x) = a_0 \sum_{n=0}^{\infty} \frac{(-1)^n \alpha(\alpha-1)\dots(\alpha-(n-1))}{(n!)^2} x^n$$

How could we write the n th term more generally?

Consider $\alpha = k$, an integer:

$$\begin{aligned} \Rightarrow k(k-1)\dots(k-(n-1)) &= \frac{k(k-1)\dots(k-(n-1))(k-n)(k-(n+1))\dots 3 \cdot 2 \cdot 1}{(k-n)(k-(n+1))\dots 3 \cdot 2 \cdot 1} \\ &= \frac{k!}{(k-n)!} \end{aligned}$$

Can we generalize? Yes, with $z! = \Gamma(z+1)$, then $\frac{\Gamma(\alpha+1)}{\Gamma(\alpha+1-n)}$ is equal to the $\alpha(\alpha-1)\dots(\alpha-(n-1))$ part.

The Gamma function is defined as

$$\Gamma(x) = \int_0^{\infty} e^{-t} t^{x-1} dt \quad \text{for } x > 0 \text{ (real)}$$

$$\Gamma(1) = \int_0^{\infty} e^{-t} dt = -e^{-t} \Big|_0^{\infty} = 1$$

We can integrate by parts to show that $\Gamma(x+1) = x\Gamma(x) = x(x-1)\Gamma(x-1)$
 $\xrightarrow{x=n \text{ integer}} \Gamma(n+1) = n!$

$$\left[\text{eg. } u = e^{-t} \Rightarrow du = -e^{-t} dt. \quad dv = t^{x-1} dt \Rightarrow v = \frac{t^x}{x} \right]$$

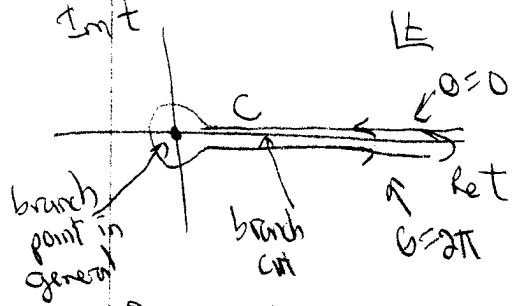
$$\Rightarrow \Gamma(x) = \frac{e^{-t} t^x}{x} \Big|_0^{\infty} + \int \frac{t^x}{x} e^{-t} dt = \frac{1}{x} \Gamma[x+1]$$

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Note that

$$\int_{-\infty}^{\infty} e^{-u^2} du = 2 \int_0^{\infty} e^{-u^2} du = 2 \int_0^{\infty} e^{-t} t^{-1/2} dt = \Gamma(1/2)!$$

$u = t^{1/2}$
 $du = \frac{1}{2} \frac{dt}{t^{1/2}}$

How do we define the integral for $\text{Re}(z) > 0$? Use a contour integral.



Use this contour so that we include the top of the branch backwards and the bottom from $\text{Re } t = 0$ to ∞ , with $\theta = 2\pi$.

The little circle around the branch point vanishes:

$$\int_C t^{z-1} e^{-t} dt = \int_0^{2\pi} (\epsilon e^{i\theta})^{z-1} e^{-\epsilon e^{i\theta}} i\epsilon e^{i\theta} d\theta$$

$$\xrightarrow{\epsilon \rightarrow 0} \epsilon^z \int_0^{2\pi} e^{iz\theta} i d\theta$$

$$= \frac{\epsilon^z}{z} (e^{2\pi iz} - 1) \xrightarrow{\epsilon \rightarrow 0} 0 \text{ for } \text{Re}(z) > 0$$

On the bottom of the branch, we get an extra $e^{2\pi iz}$, so

$$\Gamma(z) = \frac{1}{e^{2\pi iz} - 1} \int_C t^{z-1} e^{-t} dt$$

bottom of cut top of cut C Re z > 0

When $z = n$ positive integer, define as limit. There are simple poles for $z = \text{non-negative integer}$.

Ok, but what about $\Gamma(-1/2)$? Define by analytic continuation using

$$\Gamma(z) = \Gamma(z+1)/z \text{ sufficient many times. Eg. } \Gamma(-1/2) = \Gamma(1/2)/(-1/2)$$

(repeat until $\text{Re}(z+1) > 0$)

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"Practical Points Concerning the Solution of the Schrödinger Equation"

- By John M. Blatt \Rightarrow online handout
- Numerov method (less general than Runge-Kutta but more effective for Schrödinger equation usually)

To solve a differential equation numerically, you will usually use a "packaged" library routine, either in Mathematica or MATLAB or from a numerical library in C++, Fortran, Python, ...

- But you may sometimes need to implement your own solver.

Basic plan: approximate derivatives using Taylor expansion.

- For initial value problem, input starting values and integrate (that is, solve the equation) step-by-step.
- Works best for smooth, slowly varying function \Rightarrow remove rapid or non-polynomial parts if possible for greater accuracy.

Consider solving a one-variable S-equation for a bound-state energy $E < 0$:

$$-\frac{\hbar^2}{2m} \frac{d^2 u}{dx^2} + V(x)u(x) = Eu(x) \Rightarrow \boxed{\frac{d^2 u}{dx^2} = f(x)u(x)} \text{ with } \boxed{f(x) = \frac{2m}{\hbar^2}(V(x) - E)}$$

- Assume $V(x) \rightarrow 0$ as $x \rightarrow \infty$ and negative somewhere (so a bound state is possible)
- Assume $u(x=0) = 0$. Why?
- Want $u(x)$ to be "bounded and square-integrable" \Rightarrow normalizable
so $\int \text{probability} = 1$
- As a differential equation, this is linear, 2nd-order, self-adjoint (Hermitian)
No first derivative. \leftarrow why?

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Consider the Taylor expansions about x with $\Delta x = \pm h$:

$$u(x+h) = \sum_{n=0}^{\infty} \frac{h^n}{n!} u^{(n)}(x) \quad u(x-h) = \sum_{n=0}^{\infty} \frac{(-1)^n h^n}{n!} u^{(n)}(x)$$

We want even derivatives only \Rightarrow average

$$\frac{1}{2} [u(x+h) + u(x-h)] = u + \frac{1}{2} h^2 u^{(2)} + \frac{h^4}{4!} u^{(4)} + \frac{h^6}{6!} u^{(6)}$$

no argument means "evaluate at x "

We can eliminate $u^{(2)}(x)$ using the S-eqn: $u^{(2)}(x) = f(x)u(x)$

We can get rid of $u^{(4)}(x)$ by differentiating the above equation and subtracting:

$$\frac{1}{2} [u^{(2)}(x+h) + u^{(2)}(x-h)] = u^{(2)} + \frac{1}{2} h^2 u^{(4)} + \frac{h^4}{4!} u^{(6)} + \dots$$

$$\begin{aligned} \text{So } \frac{1}{2} [u(x+h) + u(x-h)] - \frac{h^2}{12} \frac{1}{2} [u^{(2)}(x+h) + u^{(2)}(x-h)] \\ = u + \frac{1}{2} h^2 u^{(2)} + \left(\frac{1}{6!} - \frac{1}{12 \cdot 4!}\right) h^6 u^{(6)} + \dots \end{aligned}$$

Replace $u^{(2)}$ by $f(x)u(x)$

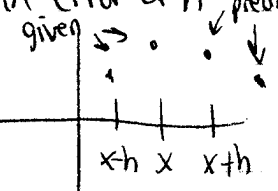
$$\begin{aligned} \Rightarrow \frac{1}{2} [u(x+h) + u(x-h)] - \frac{1}{24} h^2 [f(x+h)u(x+h) + f(x-h)u(x-h)] \\ = u(x) + \frac{1}{2} h^2 f(x)u(x) - \frac{1}{480} h^6 u^{(6)} + \dots \end{aligned}$$

Define dimensionless $T(x) \equiv \frac{h^2}{12} f(x) = \frac{h^2}{12} \frac{2m}{\hbar^2} [V(x) - E]$
and gather all the $u(x+h)$, $u(x)$, $u(x-h)$ terms: (multiply by 2)

$$(1 - T(x+h))u(x+h) + (1 - T(x-h))u(x-h) = (2 + 10T(x))u(x) - \frac{h^6}{240} u^{(6)}$$

Plan: knowing $u(x-h)$ and $u(x)$, we can find $u(x+h)$ with error $\propto h^6$ predict

$$\Rightarrow u(x+h) = \frac{1}{1 - T(x+h)} \left[-(1 - T(x-h))u(x-h) + (2 + 10T(x))u(x) \right] + O(h^6 u^{(6)})$$



3-point method with high order error, stable: unlike some other rules.

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Notes:

• We need $u(0)$ and $u(h)$ [or $u(h)$, $u(2h)$] to get started: series solution!

• $T(x)$ is known but possibly only at $x=0, h, 2h, \dots, x_{max}$

• Wait: isn't $x_{max} = \infty$? Not on the computer. Either x_{max} is large enough that $u(x_{max}) = 0$ is a negligible distortion or one matches to a exact solution (integrating in).

• You can't just take h smaller and smaller to improve accuracy
 \Rightarrow eventually round-off wins: numbers have a finite number of digits precision when stored on computers, and finer cancellations mean fewer digits precision after.

• For bound states, integrate out from the origin and in from infinity to go in the direction that $|u(x)|$ increases.

• avoids error contributions from growing exponentially or as a power law.

• How to find eigenvalues? (Later!)

• We can estimate errors for $V(x)$ such that $F(x)$ is slowly varying compared to the step size.

• If $F(x)$ is positive, then $F(x) \sim +x^2$ and $u(x)$ is roughly $u(x) \sim e^{\pm \sqrt{F(x)} x}$

• when $F(x)$ is negative, $u(x) \sim \sin(-\sqrt{F(x)} x - b)$

• In either case

$u^{(b)}(x) \approx [F(x)]^3 u(x)$ (error per step is $\frac{h^6}{240} u^{(6)}$)

so with each step, the error is

$\Rightarrow \frac{\text{relative error}}{\text{step}} = \frac{\text{error in } u(x+h)}{u(x)} = \frac{-\frac{h^6}{240} [F(x)]^3 u(x)}{u(x)} = -\frac{h^6}{10} [T(x)]^3$

So we can determine on h to use if we know how many steps is feasible and the desired tolerance. Eg. 1% accuracy and 500 steps $\Rightarrow |T(x)| \leq 0.01$ is an upper limit. Can adjust h to keep $T(x)$ near this limit. \Rightarrow Adaptive. More later!

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Fourier Series: Pass 1

In our brief look at series solutions to differential equations, all of the equations were linear: only single powers of y and its derivatives.

• Jackson, in the introduction to his text on Classical Electrodynamics, argues that linear systems are all he needs to consider.

• More generally we have to consider scales and ensure that $y(x)$ doesn't get "unphysically" large.

Linearity means that given two solutions $y_1(x)$ and $y_2(x)$, the linear sum $C_1 y_1 + C_2 y_2$ is also a solution. E.g. for $y'' + \alpha y = 0$

• Conversely, if we have something like $y'' + \alpha y^2 = 0$, the linear combination doesn't work because we have cross terms.

You recognize the physics of this property of linearity as the principle of superposition.

• It means we can make complicated solutions by adding together simple ones

• But also that we can decompose complicated solutions (essentially any we would encounter in a physics problem) into simple ones.

• One choice of simple functions for $f(x)$ in $0 \leq x \leq 2\pi$ [also written $x \in [0, 2\pi]$] are sines and cosines, or e^{inx} 's

$$\Rightarrow f(x) = \sum_{n \neq 0} (a_n \sin nx + b_n \cos nx) = \sum_{n=-\infty}^{\infty} c_n e^{inx}$$

↑ ↓
↑ ↓

real
complex

Core competencies:

1. finding coefficients
2. basic examples: square wave, saw tooth → behavior of series (Gibb's overshoot)
3. solving certain diff eqs (which ones, how to do it)